

How to Make a Bipartite Graph DM-irreducible by Adding Edges

Satoru Iwata¹, Jun Kato², Yutaro Yamaguchi³

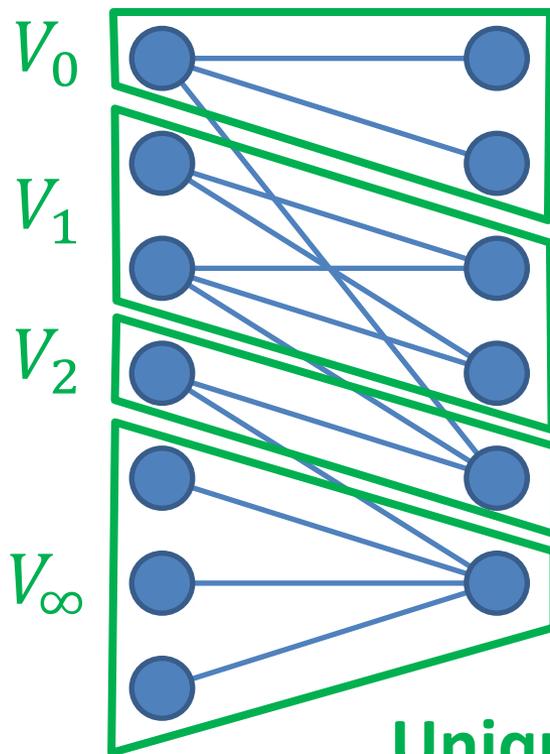
1. University of Tokyo, Japan.
2. TOYOTA Motor Corporation, Japan.
3. Osaka University, Japan.

Shonan Meeting 071 @Shonan April 12, 2016

Dulmage–Mendelsohn Decomposition

[Dulmage–Mendelsohn 1958,59]

Given $G = (V^+, V^-; E)$: Bipartite Graph



- $|V_0^+| < |V_0^-|$ or $V_0 = \emptyset$
- $|V_i^+| = |V_i^-|$ ($i \neq 0, \infty$)
- $|V_\infty^+| > |V_\infty^-|$ or $V_\infty = \emptyset$

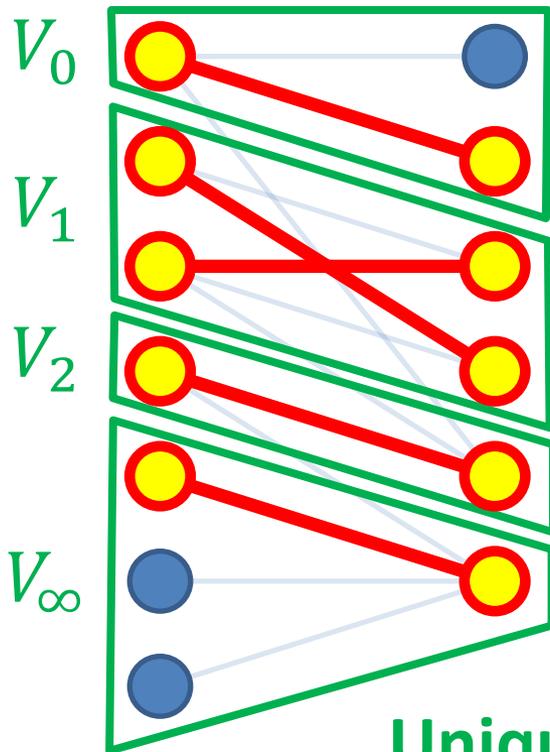
Unique Partition of Vertex Set

reflecting Structure of **Maximum Matchings**

Dulmage–Mendelsohn Decomposition

[Dulmage–Mendelsohn 1958,59]

Given $G = (V^+, V^-; E)$: Bipartite Graph



- $|V_0^+| < |V_0^-|$ or $V_0 = \emptyset$
- $|V_i^+| = |V_i^-|$ ($i \neq 0, \infty$)
- $|V_\infty^+| > |V_\infty^-|$ or $V_\infty = \emptyset$
- \forall **Max. Matching** in G is a union of **Perfect Matchings** in $G[V_i]$

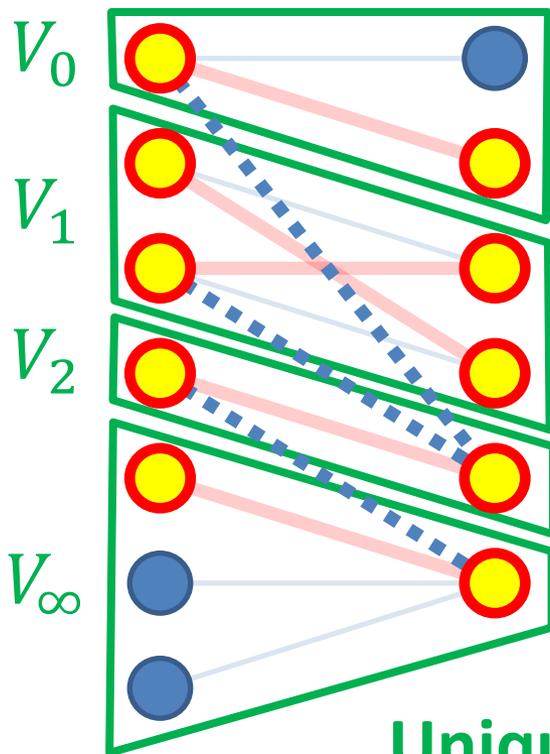
Unique Partition of Vertex Set

reflecting Structure of **Maximum Matchings**

Dulmage–Mendelsohn Decomposition

[Dulmage–Mendelsohn 1958,59]

Given $G = (V^+, V^-; E)$: Bipartite Graph



- \forall **Max. Matching** in G is a union of **Perfect Matchings** in $G[V_i]$
→ **Edges** between V_i and V_j ($i \neq j$) can**NOT** be used.

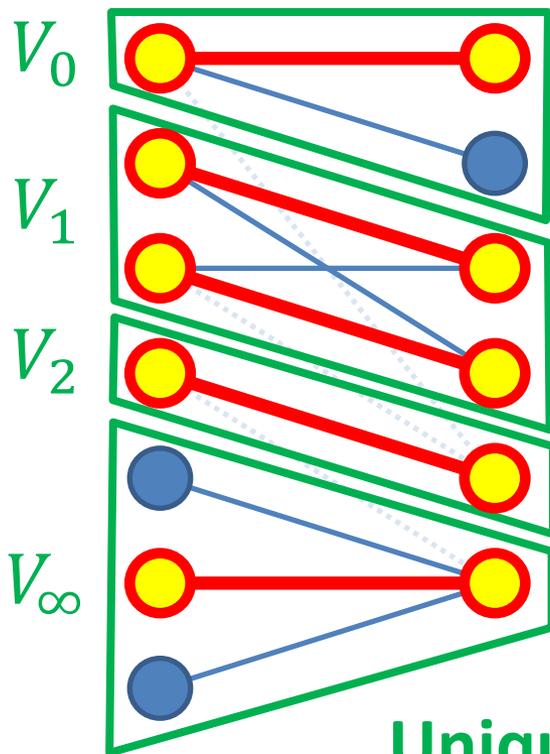
Unique Partition of Vertex Set

reflecting Structure of **Maximum Matchings**

Dulmage–Mendelsohn Decomposition

[Dulmage–Mendelsohn 1958,59]

Given $G = (V^+, V^-; E)$: Bipartite Graph



- \forall **Max. Matching** in G is a union of **Perfect Matchings** in $G[V_i]$
→ **Edges** between V_i and V_j ($i \neq j$) can**NOT** be used.
- $\forall e$: Edge in $G[V_i]$,
 \exists **Perfect Matching** in $G[V_i]$ using e

Unique Partition of Vertex Set

reflecting Structure of **Maximum Matchings**

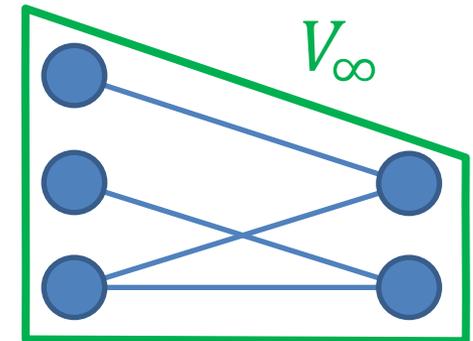
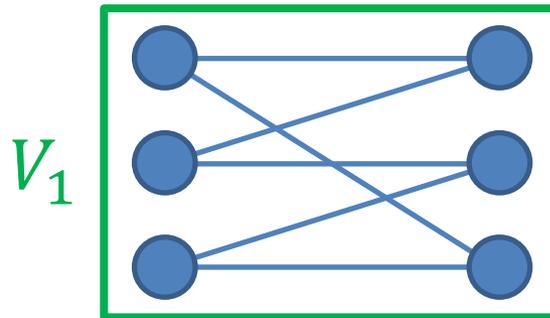
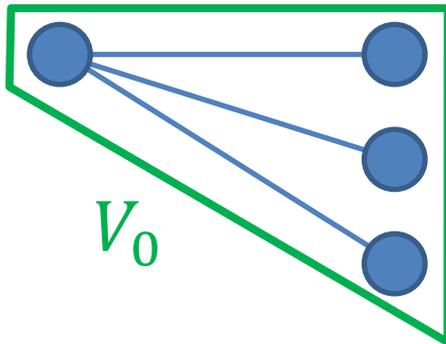
DM-irreducibility

Def.

A bipartite graph is **DM-irreducible**



The DM-decomposition consists of a single component



Obs.

A bipartite graph G is **DM-irreducible**

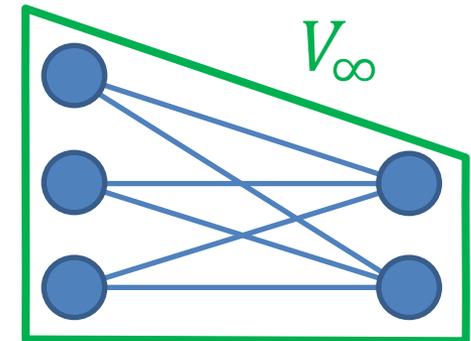
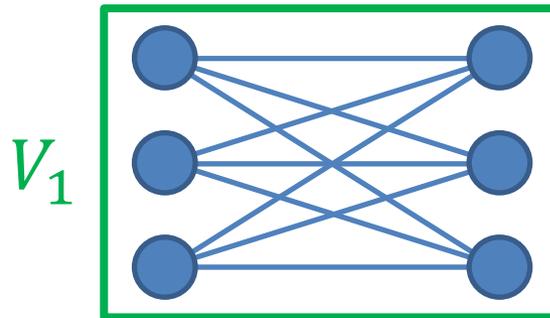
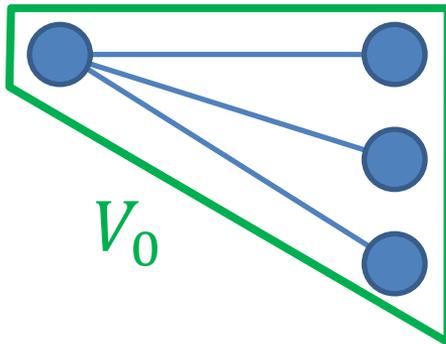


$\forall e$: Edge in G , \exists Perfect Matching in G using e

DM-irreducibility

Obs. Complete bipartite graphs are DM-irreducible.

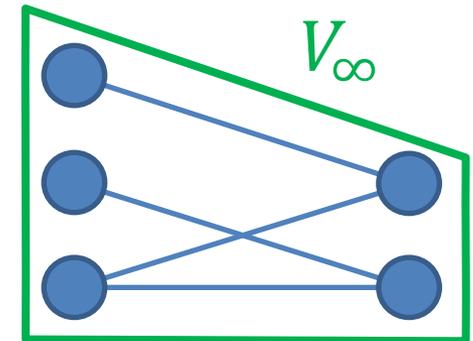
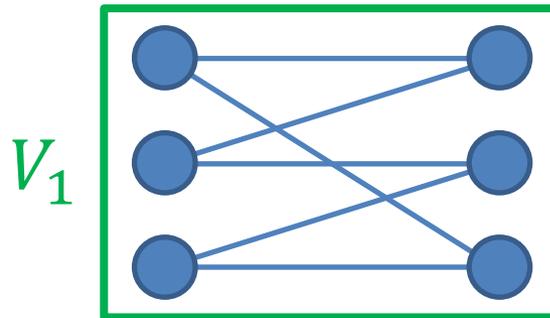
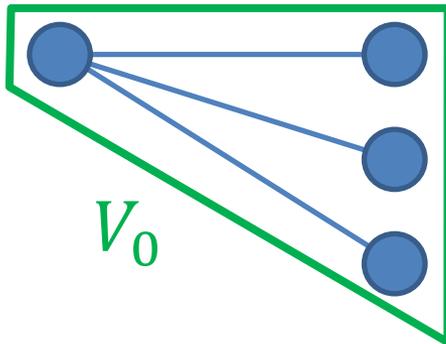
- Connected
- Every Edge is in some Perfect Matching



DM-irreducibility

Obs. Complete bipartite graphs are DM-irreducible.

- Connected
- Every Edge is in some Perfect Matching

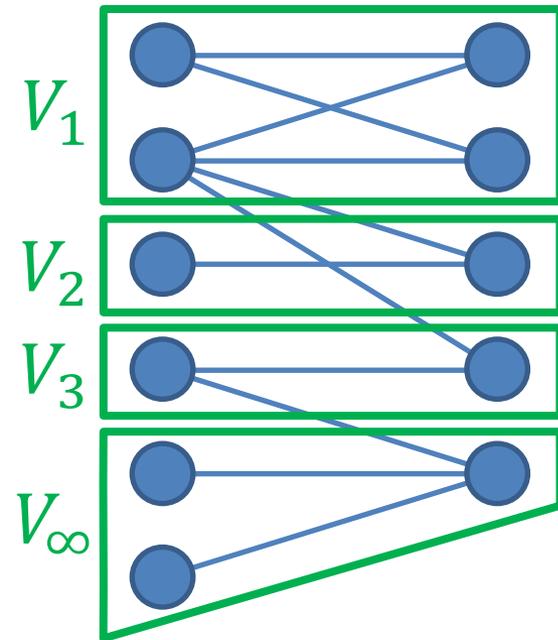
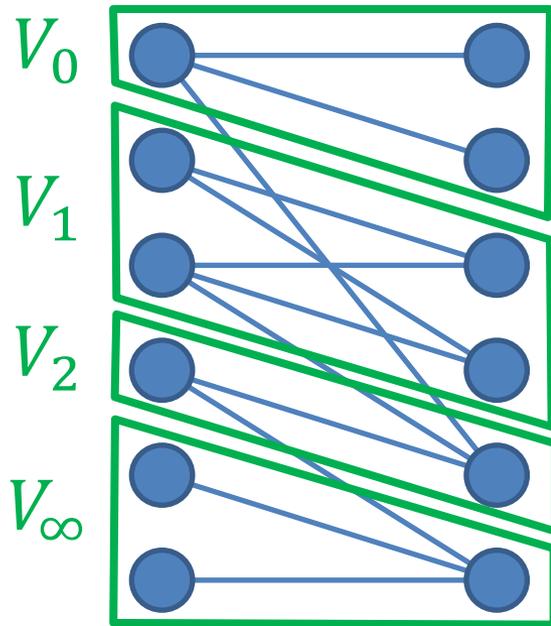


Complete $\begin{matrix} \implies \\ \nleftarrow \end{matrix}$ DM-irreducible

How many additional edges are necessary
to make a bipartite graph DM-irreducible?

Our Problem

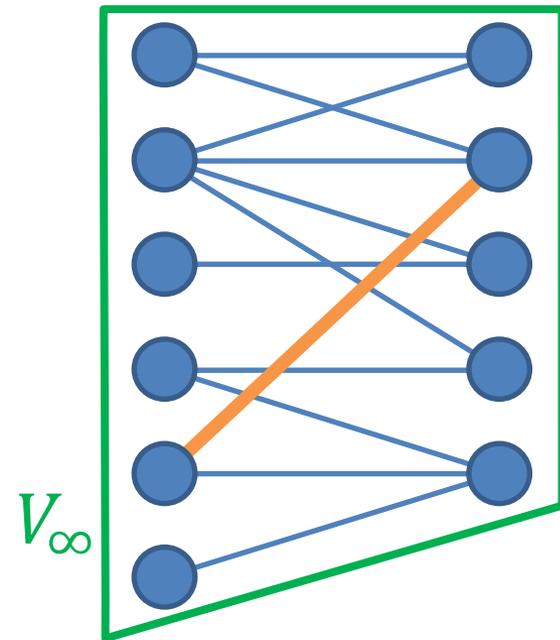
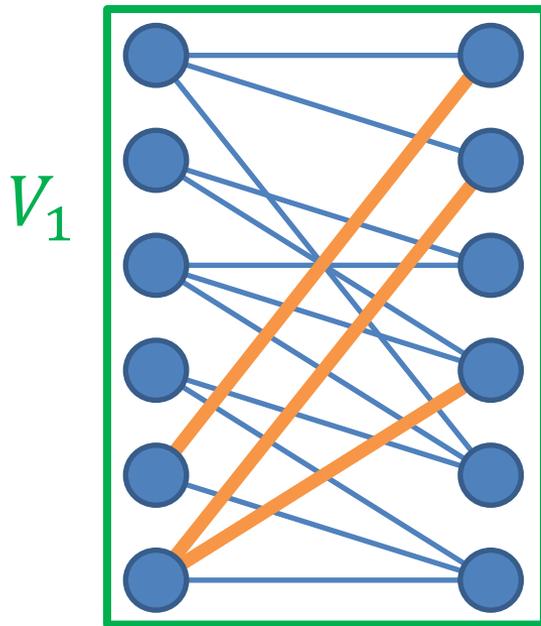
Given $G = (V^+, V^-; E)$: Bipartite Graph



Find Minimum Number of Additional Edges
to Make G **DM-irreducible**

Our Problem

Given $G = (V^+, V^-; E)$: Bipartite Graph



Find Minimum Number of Additional Edges
to Make G DM-irreducible

Our Result

Given $G = (V^+, V^-; E)$: Bipartite Graph

Find **Minimum Number of Additional Edges**
to Make G **DM-irreducible**

Thm. This problem can be solved in polynomial time.

[I.-K.-Y. 2016]

Tools

- Finding a **Maximum Matching** in a **Bipartite Graph**
- Decomposition into **Strongly Connected Components**
- Making a Digraph **Strongly Connected** by Adding Edges
- Finding **Edge-Disjoint $s-t$ Paths** in a Digraph

Outline

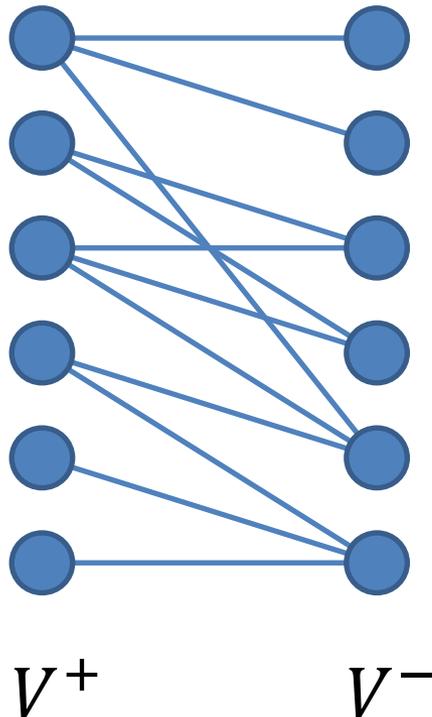
- **Preliminaries:** How to Compute DM-decomposition
 - Find a **Maximum Matching** in a Bipartite Graph
 - Decompose a Digraph into **Strongly Connected Components**
- **Result:** How to Make a Bipartite Graph DM-irreducible
 - Make a Digraph **Strongly Connected**
 - Find **Edge-Disjoint $s-t$ Paths** in a Digraph
- **Conclusion**

Outline

- Preliminaries: How to Compute DM-decomposition
 - Find a **Maximum Matching** in a Bipartite Graph
 - Decompose a Digraph into **Strongly Connected Components**
- Result: How to Make a Bipartite Graph DM-irreducible
 - Make a Digraph **Strongly Connected**
 - Find **Edge-Disjoint $s-t$ Paths** in a Digraph
- Conclusion

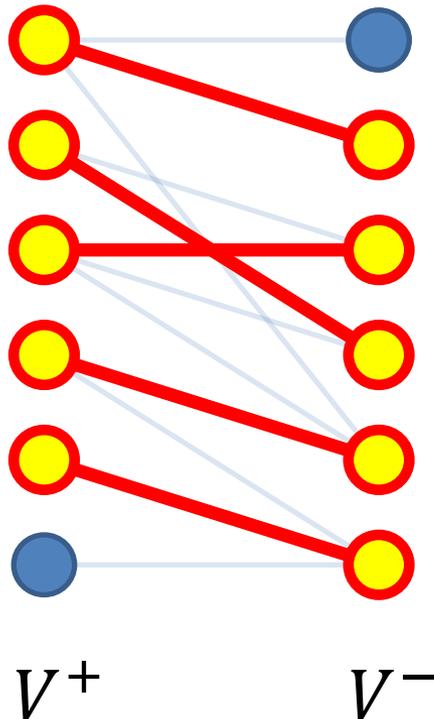
How to Compute DM-decomposition

Given $G = (V^+, V^-; E)$: Bipartite Graph



How to Compute DM-decomposition

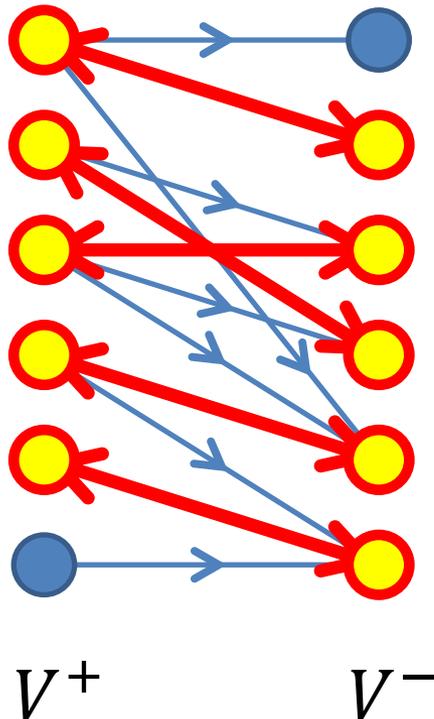
Given $G = (V^+, V^-; E)$: Bipartite Graph



- Find a Maximum Matching M in G

How to Compute DM-decomposition

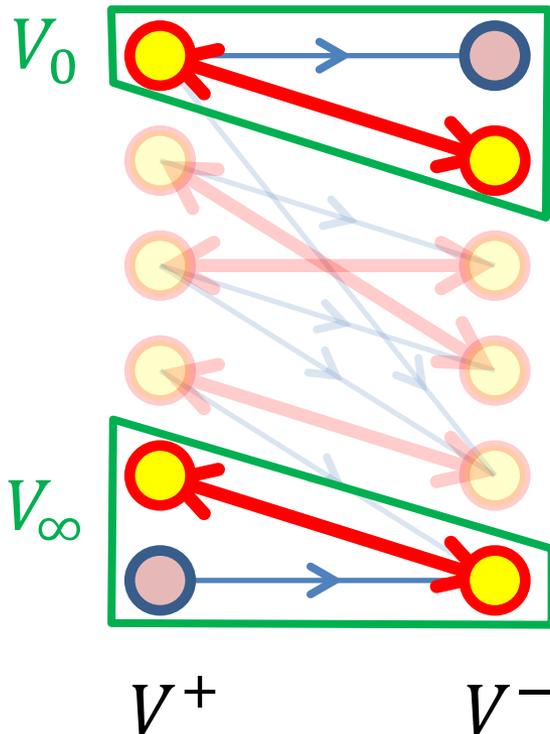
Given $G = (V^+, V^-; E)$: Bipartite Graph



- Find a Maximum Matching M in G
- Orient Edges so that
 - $M \implies$ Both Directions \leftrightarrow
 - $E \setminus M \implies$ Left to Right \rightarrow

How to Compute DM-decomposition

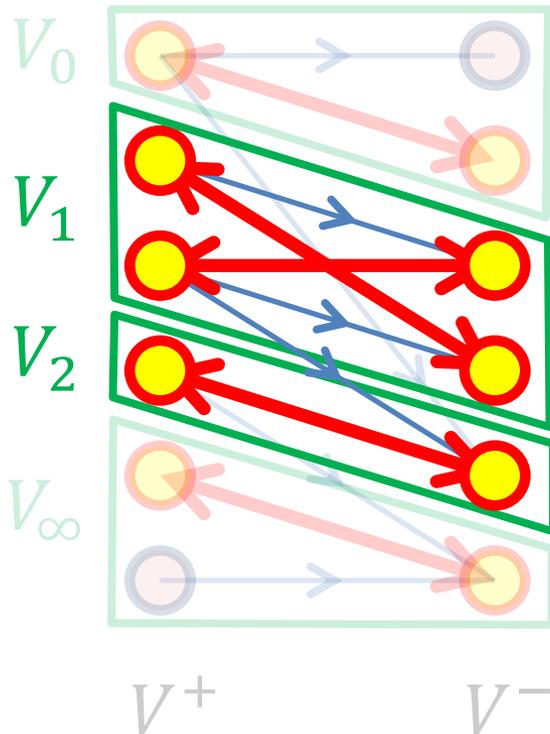
Given $G = (V^+, V^-; E)$: Bipartite Graph



- Find a Maximum Matching M in G
- Orient Edges so that
 - $M \implies$ Both Directions \leftrightarrow
 - $E \setminus M \implies$ Left to Right \rightarrow
- V_0 : Reachable to $V^- \setminus \partial^- M$
- V_∞ : Reachable from $V^+ \setminus \partial^+ M$

How to Compute DM-decomposition

Given $G = (V^+, V^-; E)$: Bipartite Graph



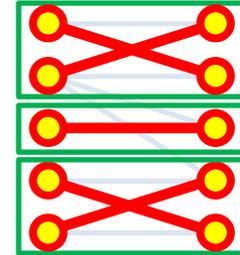
- Find a **Maximum Matching** M in G
- **Orient Edges** so that
 - $M \implies$ Both Directions \leftrightarrow
 - $E \setminus M \implies$ Left to Right \rightarrow
- V_0 : **Reachable to** $V^- \setminus \partial^- M$
- V_∞ : **Reachable from** $V^+ \setminus \partial^+ M$
- V_i : **Strongly Connected Component** of $G - V_0 - V_\infty$

Outline

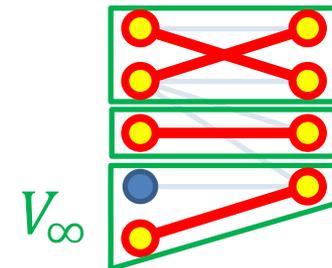
- Preliminaries: How to Compute DM-decomposition
 - Find a **Maximum Matching** in a Bipartite Graph
 - Decompose a Digraph into **Strongly Connected Components**
- **Result: How to Make a Bipartite Graph DM-irreducible**
 - Make a Digraph **Strongly Connected**
 - Find **Edge-Disjoint $s-t$ Paths** in a Digraph
- Conclusion

Case Analysis

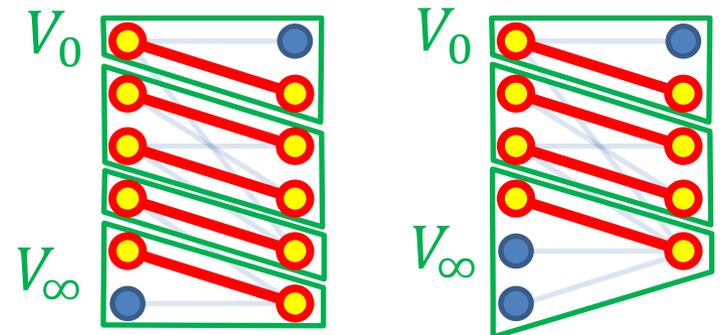
Case 1. When $V_0 = \emptyset = V_\infty$



Case 2. When $V_0 = \emptyset \neq V_\infty$

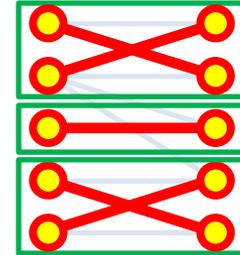


Case 3. When $V_0 \neq \emptyset \neq V_\infty$

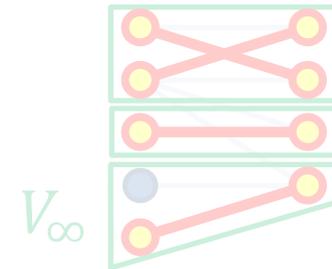


Case Analysis

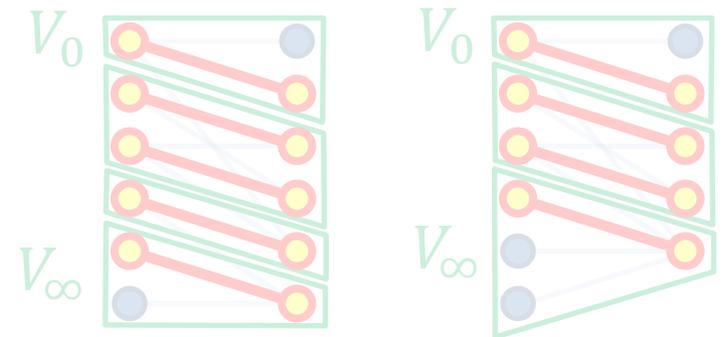
Case 1. When $V_0 = \emptyset = V_\infty$



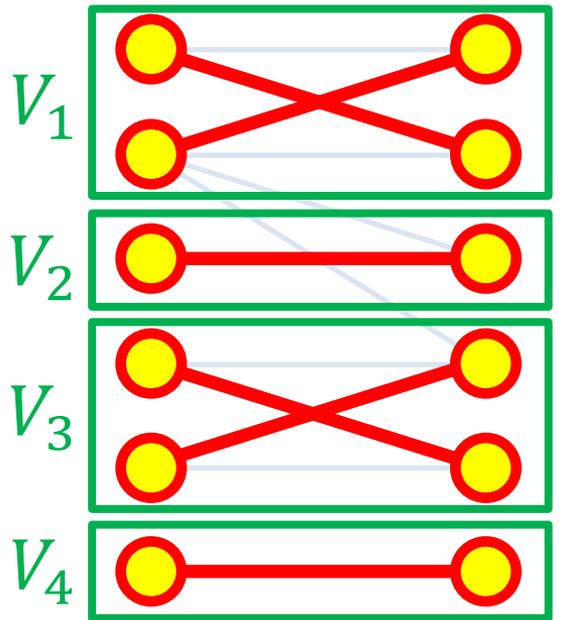
Case 2. When $V_0 = \emptyset \neq V_\infty$



Case 3. When $V_0 \neq \emptyset \neq V_\infty$



Case 1. When $V_0 = \emptyset = V_\infty$



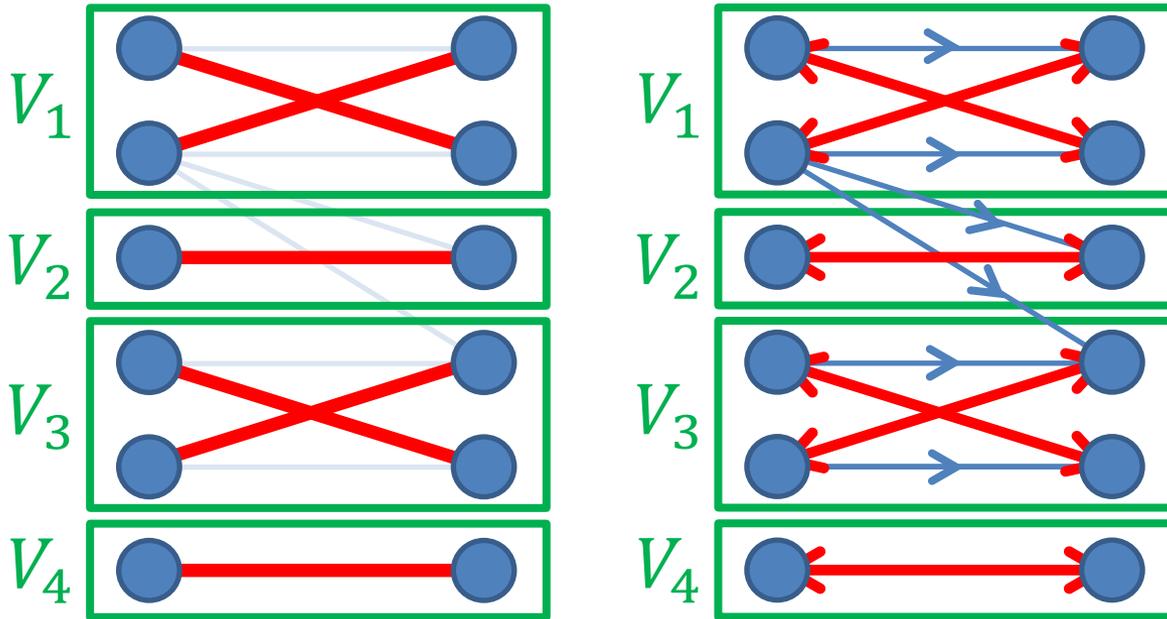
DM-decomposition

- $|V_i^+| = |V_i^-|$ ($i \neq 0, \infty$)
- \forall **Max. Matching** in G is a union of **Perfect Matchings** in $G[V_i]$



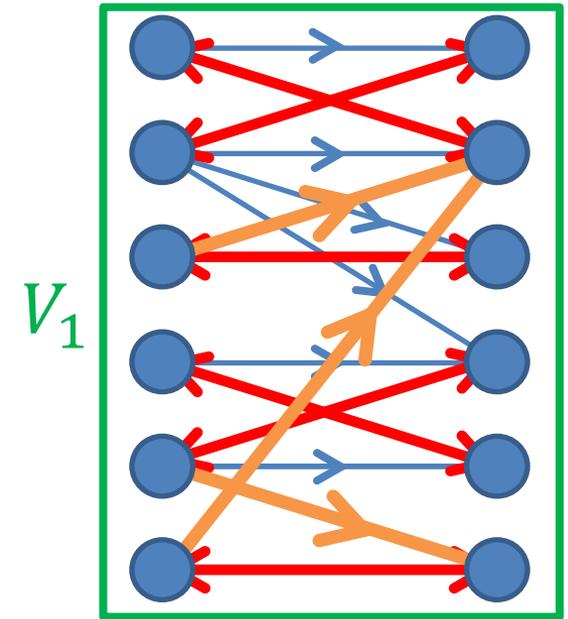
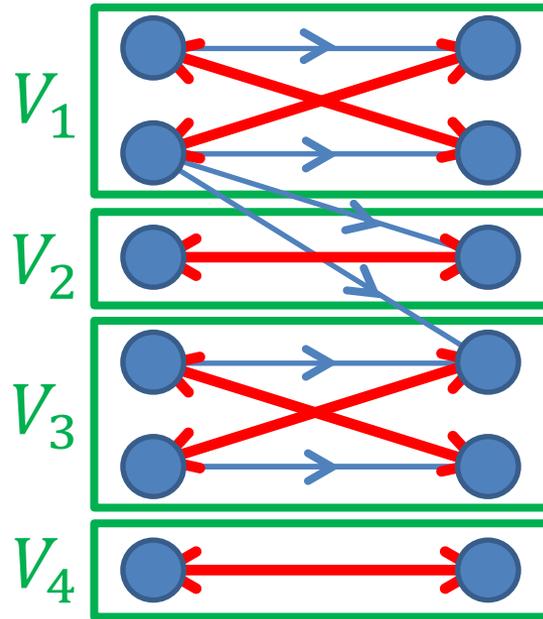
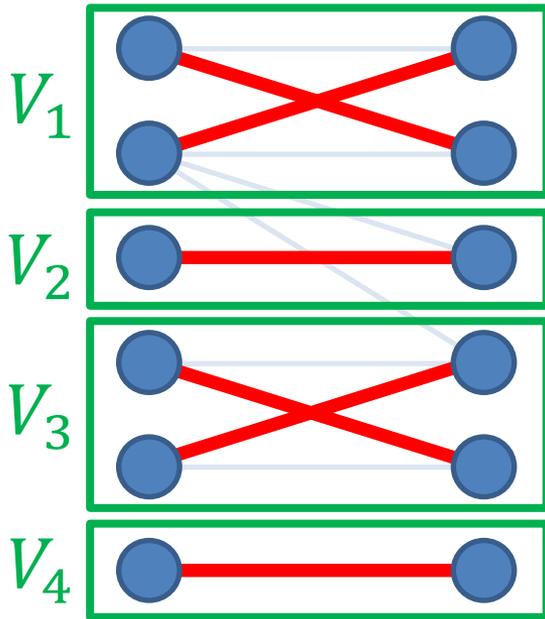
- $|V^+| = |V^-|$
- G has a **Perfect Matching**

Case 1. When $V_0 = \emptyset = V_\infty$



DM-decomposition = Strg. Conn. Comps.

Case 1. When $V_0 = \emptyset = V_\infty$

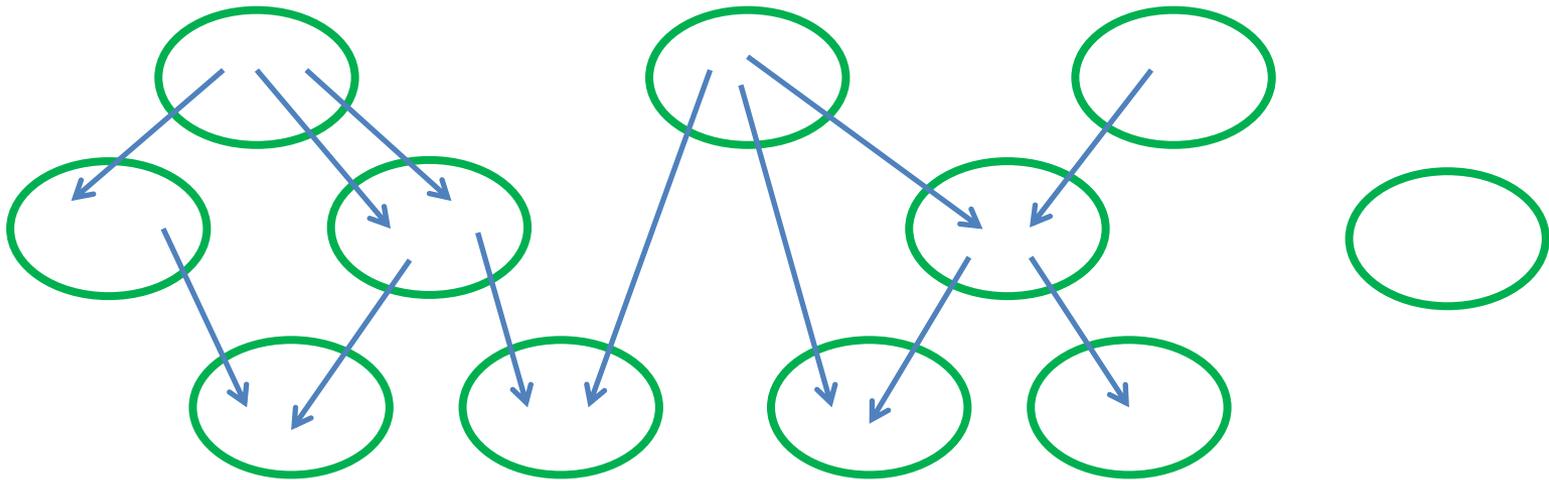


DM-decomposition = Strg. Conn. Comps. \rightarrow Make it Strg. Conn. by Adding Edges

Obs. DM-irreducibility is Equivalent to Strong Connectivity of the Oriented Graph

How to Make a Digraph Strongly Connected

Given $G = (V, E)$: Directed Graph ○: Strg. Conn. Comp.

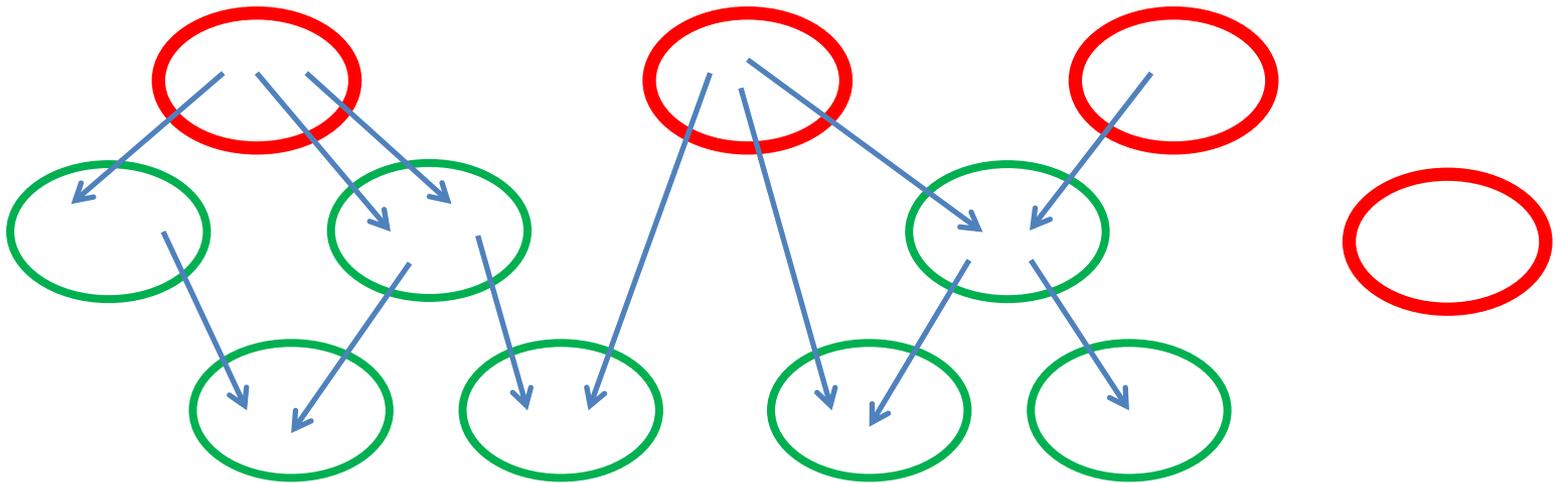


Find Minimum Number of Additional Edges to Make G **Strongly Connected**

How to Make a Digraph Strongly Connected

Given $G = (V, E)$: Directed Graph ○: Strg. Conn. Comp.

Each **Source** needs an **Entering Edge**

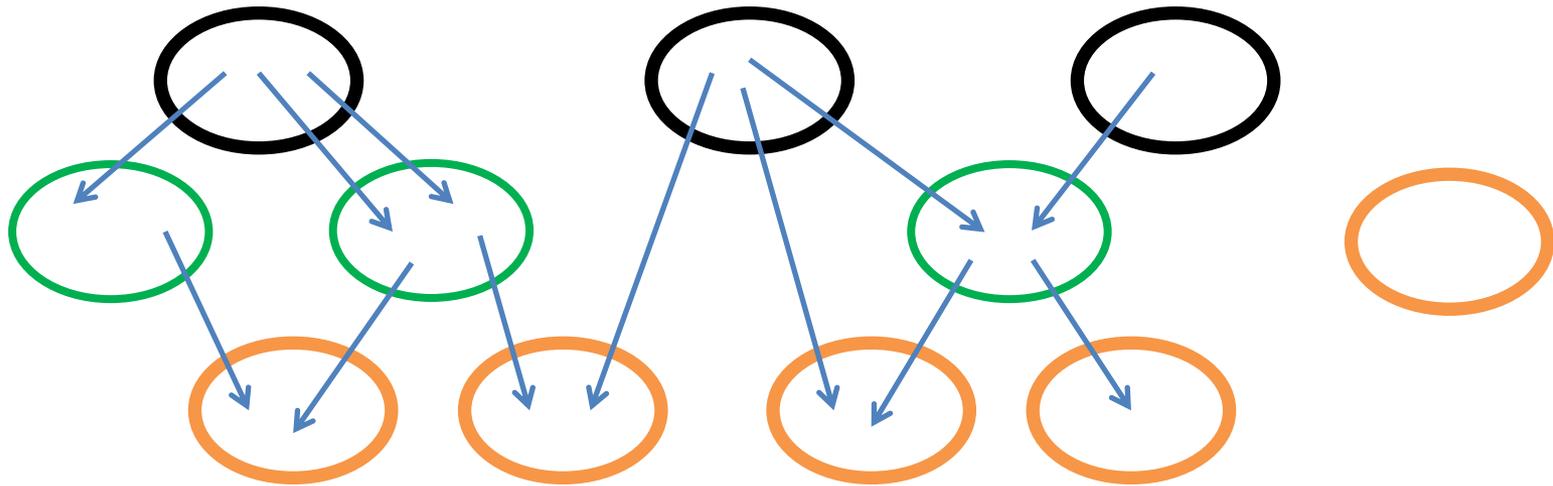


Find Minimum Number of Additional Edges to Make G **Strongly Connected**

How to Make a Digraph Strongly Connected

Given $G = (V, E)$: Directed Graph ○: Strg. Conn. Comp.

Each **Source** needs an **Entering Edge**



Each **Sink** needs a **Leaving Edge**

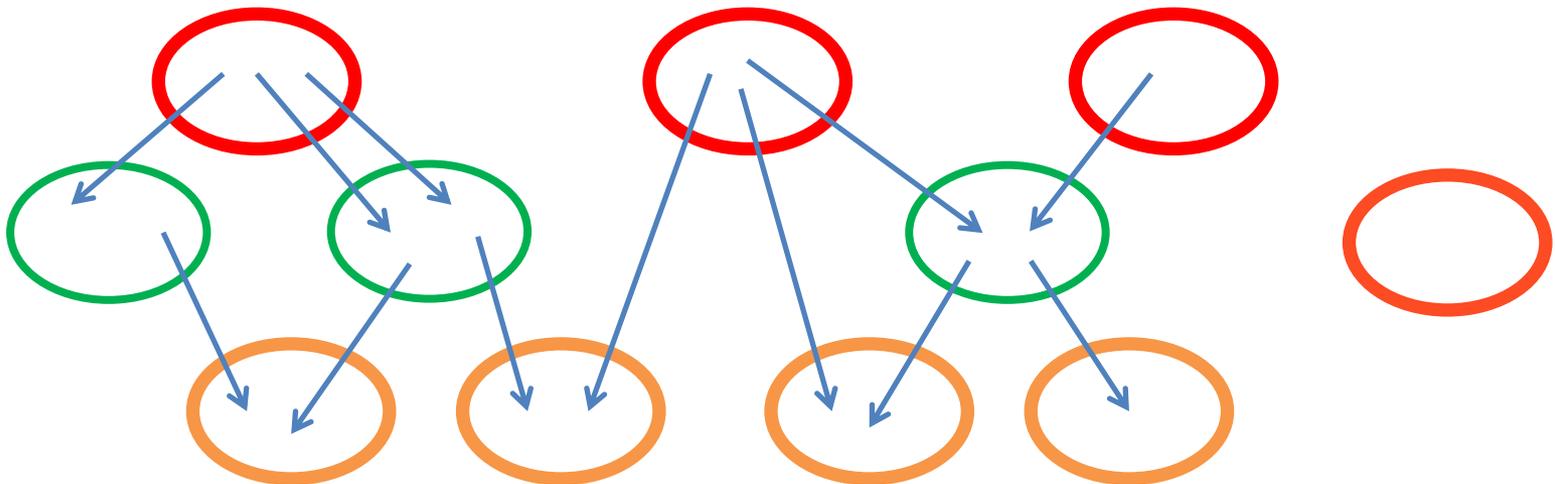
Find Minimum Number of Additional Edges
to Make G **Strongly Connected**

How to Make a Digraph Strongly Connected

Given $G = (V, E)$: Directed Graph NOT Strg. Conn.

Find Minimum Number of Additional Edges
to Make G **Strongly Connected**

Obs. $\max\{\# \text{ of Sources}, \# \text{ of Sinks}\}$ edges are Necessary.



How to Make a Digraph Strongly Connected

Given $G = (V, E)$: Directed Graph NOT Strg. Conn.

Find Minimum Number of Additional Edges
to Make G **Strongly Connected**

Obs. $\max\{\# \text{ of Sources}, \# \text{ of Sinks}\}$ edges are **Necessary**.

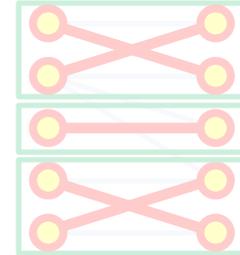
Thm. $\max\{\# \text{ of Sources}, \# \text{ of Sinks}\}$ edges are **Sufficient**.
 \exists **Polytime Algorithm** to find such Additional Edges.

[Eswaran–Tarjan 1976]

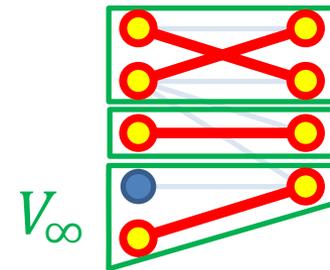
→ Case 1 is **Polytime Solvable**.

Case Analysis

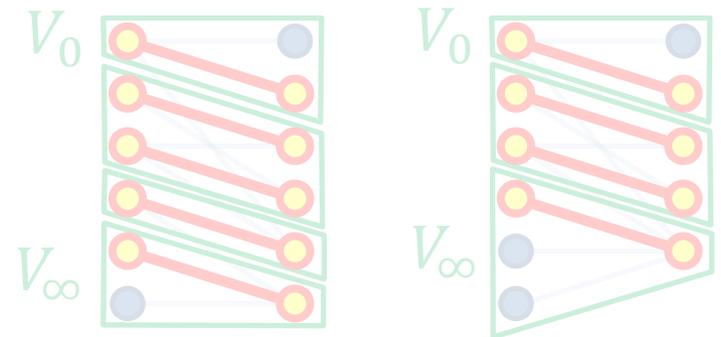
Case 1. When $V_0 = \emptyset = V_\infty$



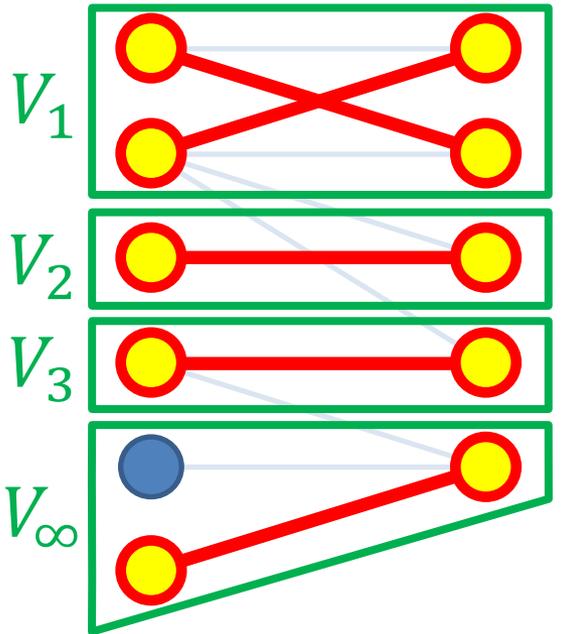
Case 2. When $V_0 = \emptyset \neq V_\infty$



Case 3. When $V_0 \neq \emptyset \neq V_\infty$



Case 2. When $V_0 = \emptyset \neq V_\infty$



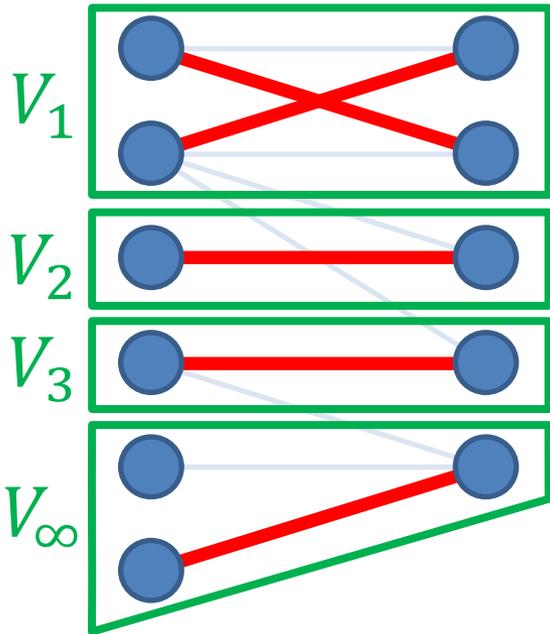
DM-decomposition

- $|V_i^+| = |V_i^-|$ ($i \neq 0, \infty$)
- $|V_\infty^+| > |V_\infty^-|$
- \forall **Max. Matching** in G is a union of **Perfect Matchings** in $G[V_i]$

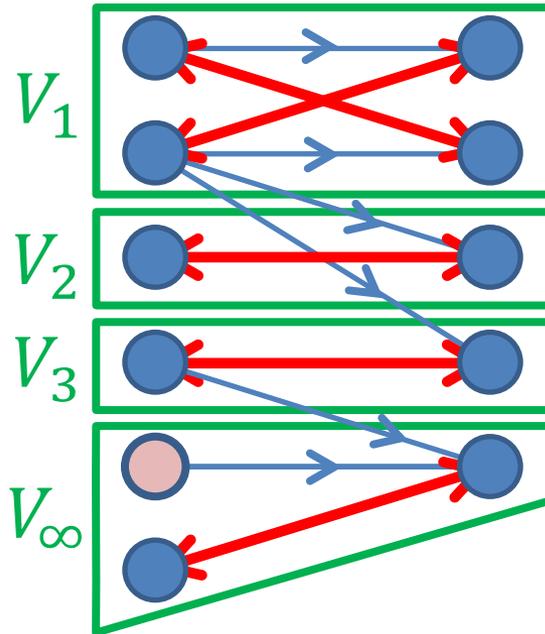


- $|V^+| > |V^-|$
- G has a **Perfect Matching**

Case 2. When $V_0 = \emptyset \neq V_\infty$



DM-decomposition



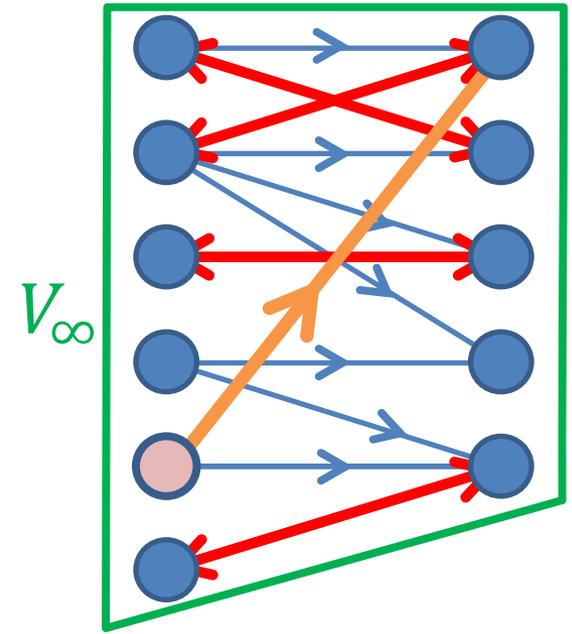
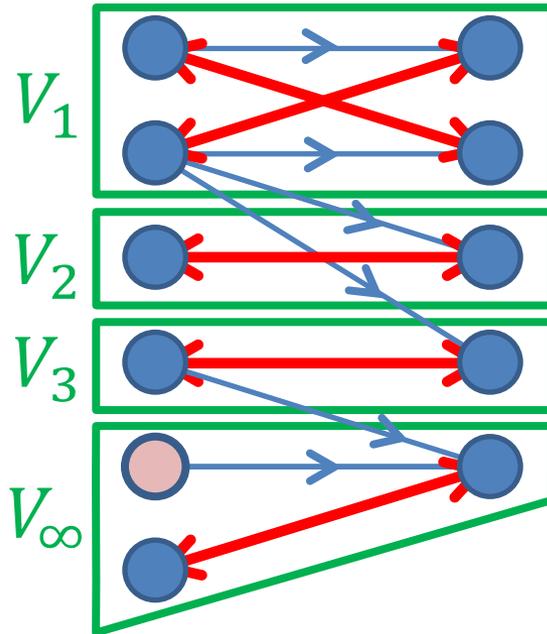
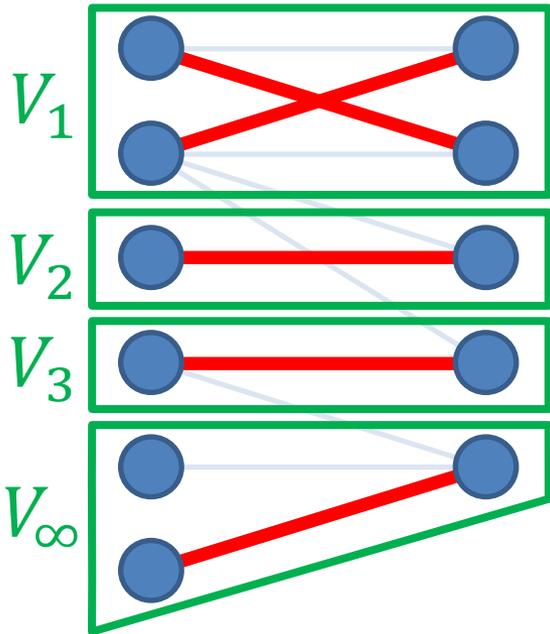
Reachability from
Exposed Vertices

+

Strg. Conn. Comps.
of the Rest

=

Case 2. When $V_0 = \emptyset \neq V_\infty$



DM-decomposition

\equiv

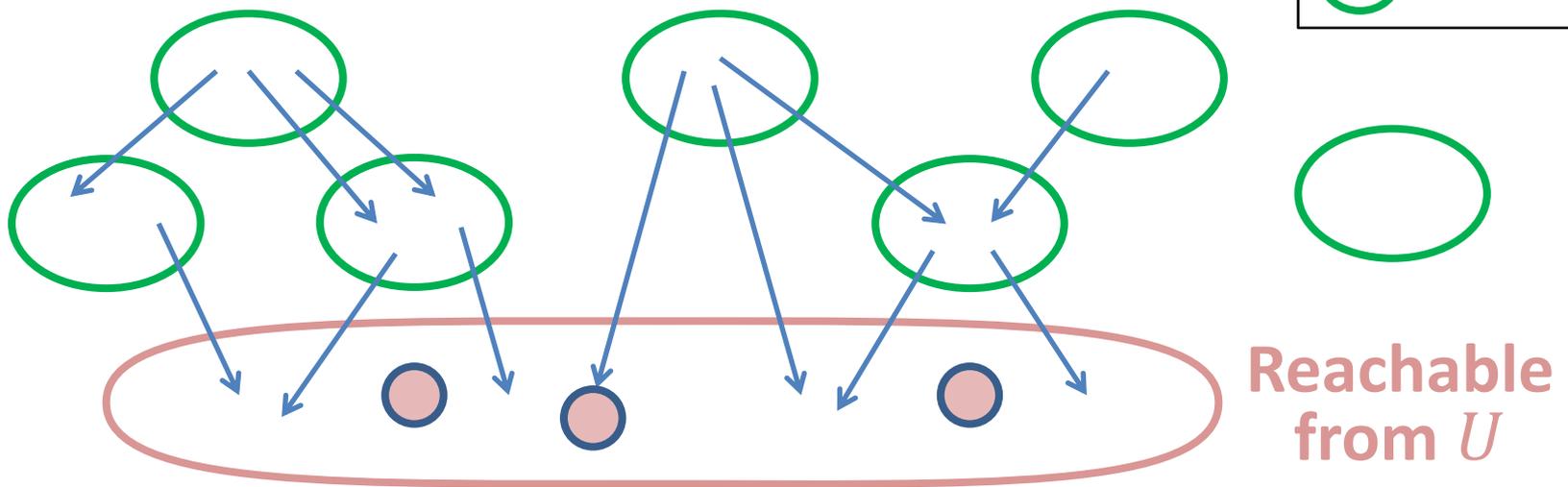
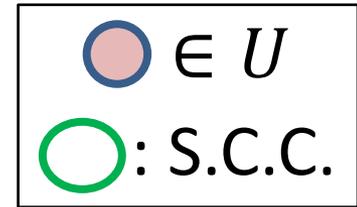
Reachability from Exposed Vertices
+
Strg. Conn. Comps. of the Rest

\rightarrow

Make ALL Vertices Reachable from Exposed Vertices by Adding Edges

How to Achieve such Reachability

Given $G = (V, E)$: Directed Graph, $U \subseteq V$

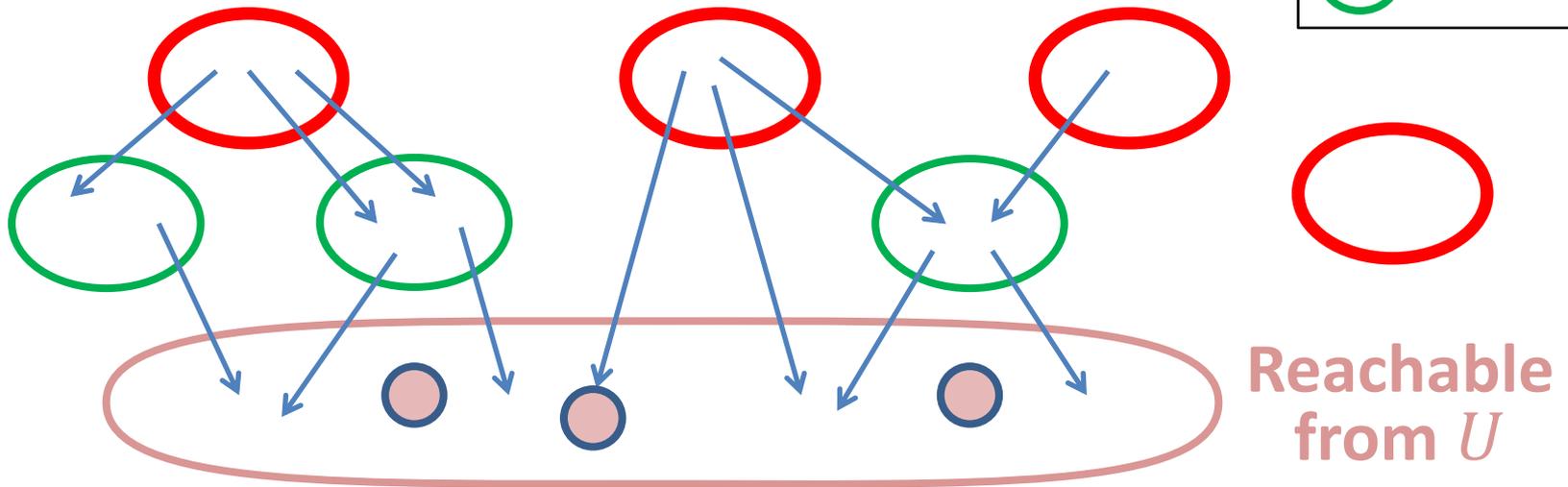
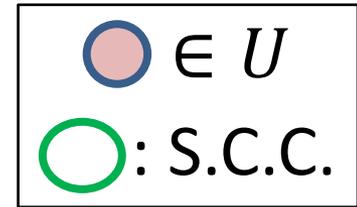


Find Minimum Number of Additional Edges to Make **ALL Vertices** Reachable from U

How to Achieve such Reachability

Given $G = (V, E)$: Directed Graph, $U \subseteq V$

Each **Source** needs an **Entering Edge**

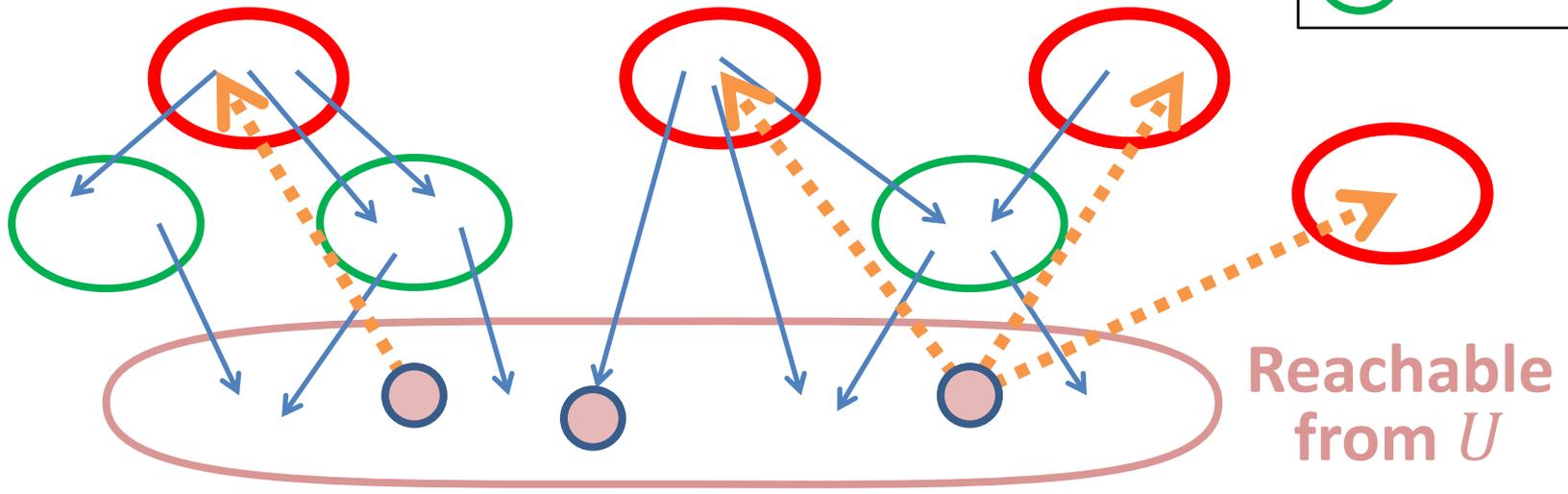
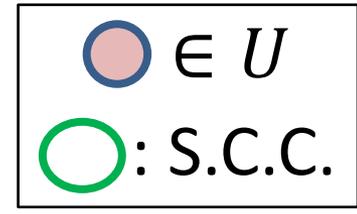


Find Minimum Number of Additional Edges to Make **ALL Vertices** **Reachable from U**

How to Achieve such Reachability

Given $G = (V, E)$: Directed Graph, $U \subseteq V$

Sufficient!! Each **Source** needs an **Entering Edge**



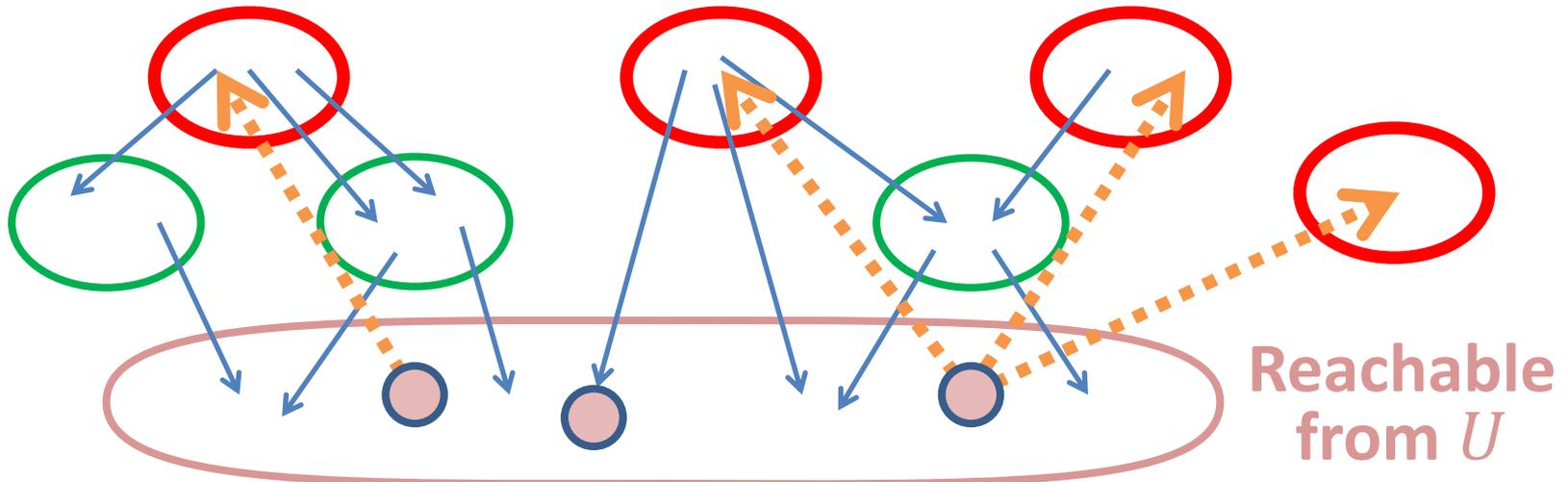
Find Minimum Number of Additional Edges to Make **ALL Vertices** **Reachable from U**

How to Make a Digraph Strongly Connected

Given $G = (V, E)$: Directed Graph, $U \subseteq V$

Find Minimum Number of Additional Edges to Make **ALL Vertices** Reachable from U

Obs. (# of **Sources**) edges are **Necessary and Sufficient**.



Summary of Cases 1 and 2

Case 1. $|V^+| = |V^-|$ and G has a Perfect Matching

$$\text{OPT} = \max\{\# \text{ of Sources, } \# \text{ of Sinks}\}$$

Case 2. $|V^+| > |V^-|$ and G has a Perfect Matching

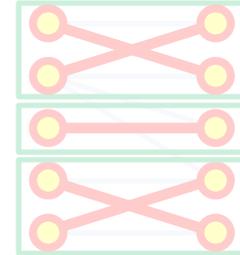
$$\text{OPT} = (\# \text{ of Sources NOT Reachable from } V_\infty)$$

Case 2'. $|V^+| < |V^-|$ and G has a Perfect Matching

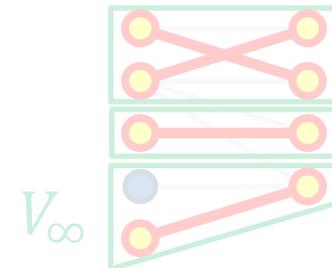
$$\text{OPT} = (\# \text{ of Sinks NOT Reachable to } V_0)$$

Case Analysis

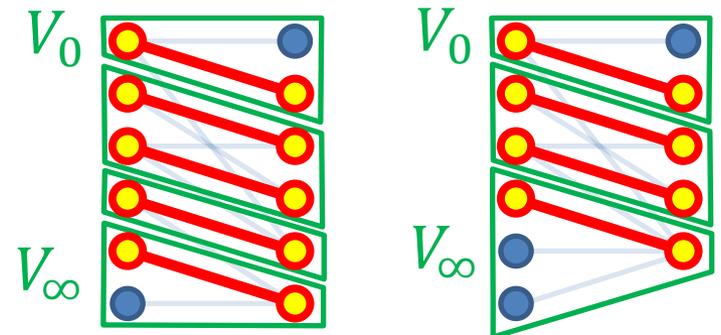
Case 1. When $V_0 = \emptyset = V_\infty$



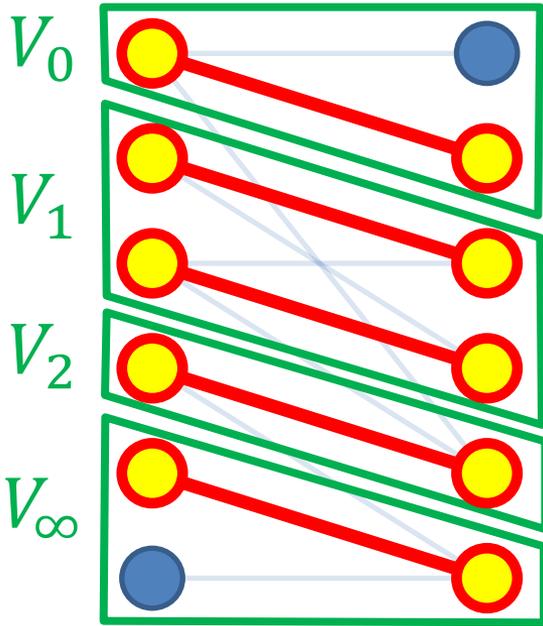
Case 2. When $V_0 = \emptyset \neq V_\infty$



Case 3. When $V_0 \neq \emptyset \neq V_\infty$



Case 3. When $V_0 \neq \emptyset \neq V_\infty$



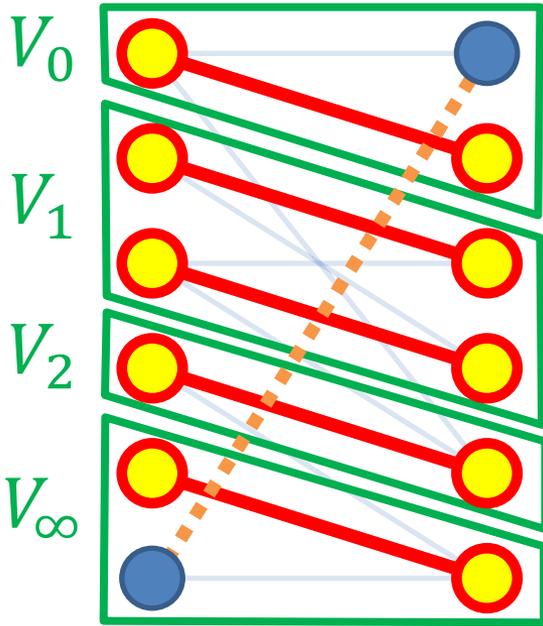
DM-decomposition

- $|V_0^+| < |V_0^-|$
- $|V_i^+| = |V_i^-| \quad (i \neq 0, \infty)$
- $|V_\infty^+| > |V_\infty^-|$
- \forall **Max. Matching** in G is a union of **Perfect Matchings** in $G[V_i]$



G has NO **Perfect Matching**

Case 3. When $V_0 \neq \emptyset \neq V_\infty$



DM-decomposition

- $|V_0^+| < |V_0^-|$
- $|V_i^+| = |V_i^-| \quad (i \neq 0, \infty)$
- $|V_\infty^+| > |V_\infty^-|$
- \forall **Max. Matching** in G is a union of **Perfect Matchings** in $G[V_i]$

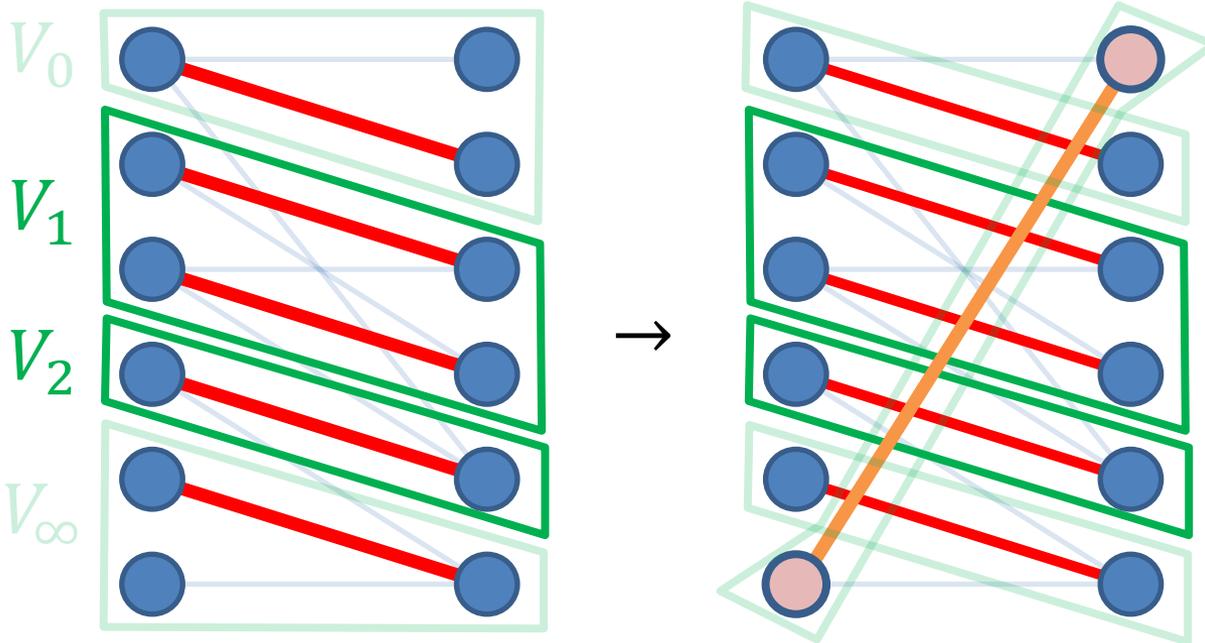


G has NO **Perfect Matching**

Idea

Adding Edges to Reduce to Cases 1,2 (\exists **Perfect Matching**)

Key Observation



DM-decomposition

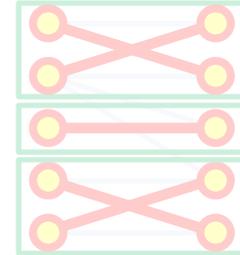
Idea

Adding Edges to Reduce to Cases 1,2 (\exists **Perfect Matching**)

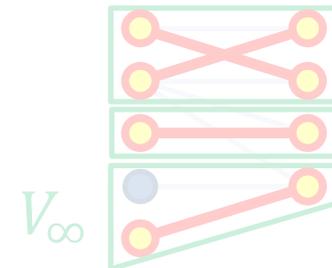
Connecting Exposed Vertices
↓
 \exists **New Max. Matching** including **the Original**
↓
Each V_i ($i \neq 0, \infty$) remains as it was

Case Analysis

Case 1. When $V_0 = \emptyset = V_\infty$

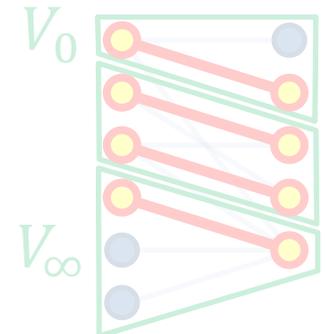
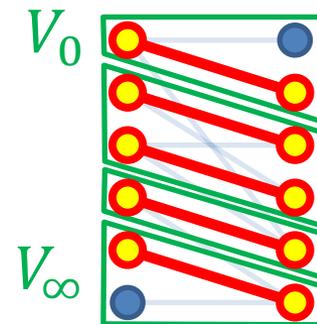


Case 2. When $V_0 = \emptyset \neq V_\infty$



Case 3. When $V_0 \neq \emptyset \neq V_\infty$

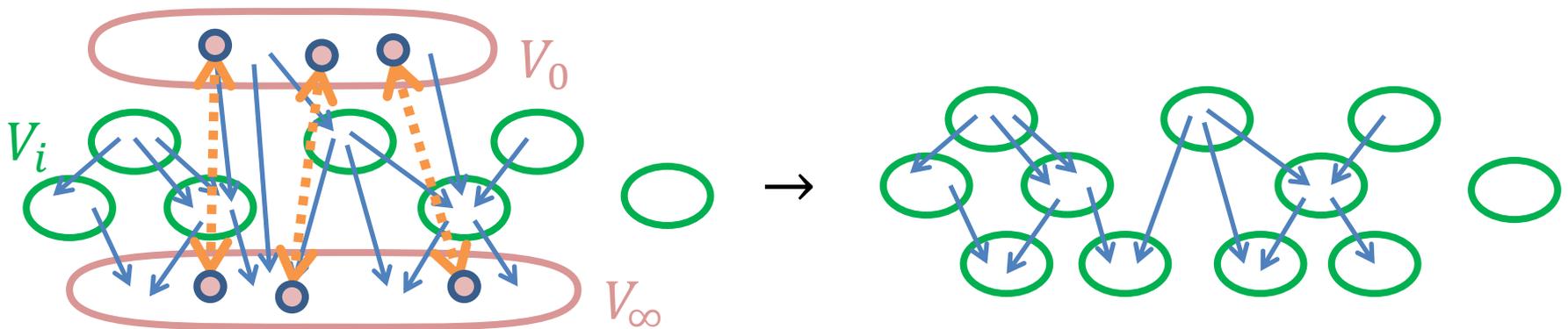
Case 3.1. $|V^+| = |V^-|$



Case 3.1. When $|V^+| = |V^-|$

Idea

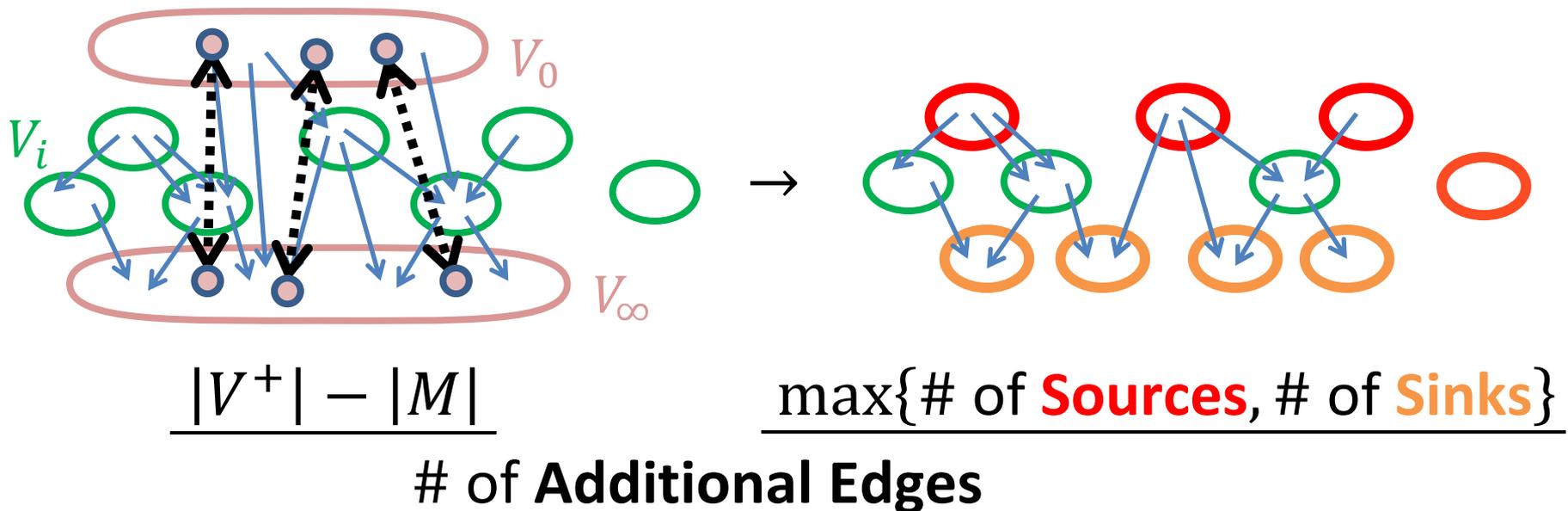
Adding Edges to Reduce to Case 1 (\exists Perfect Matching)
between Exposed Vertices
in a Max. Matching M in G



Case 3.1. When $|V^+| = |V^-|$

Idea

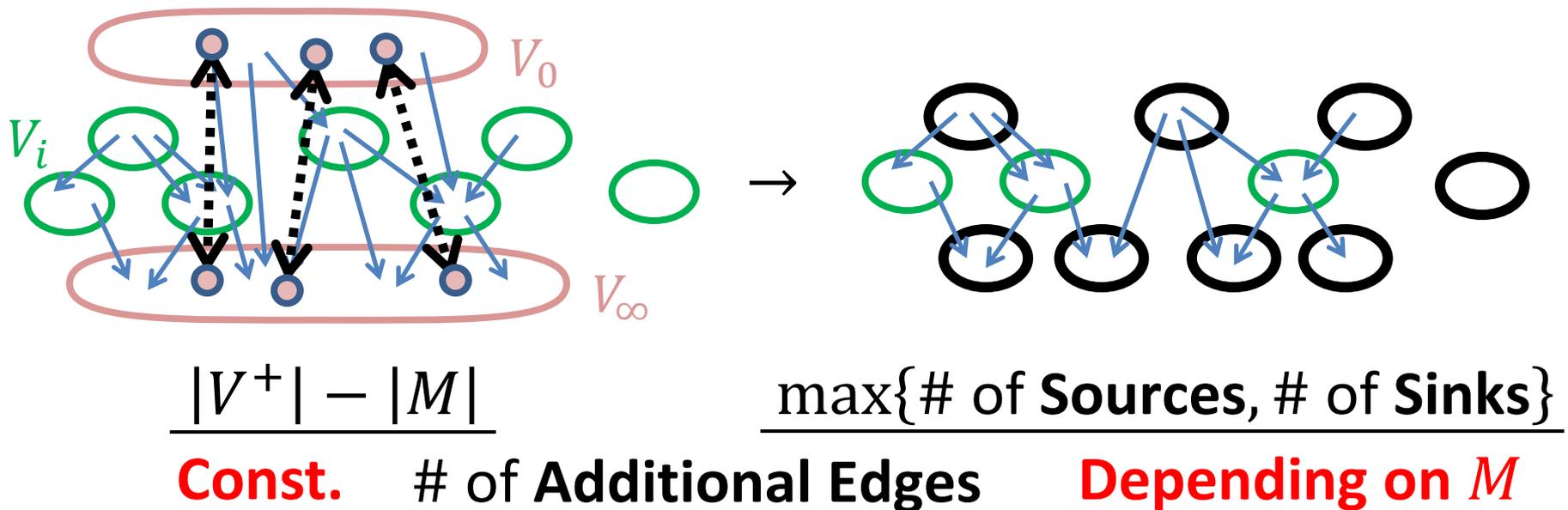
Adding Edges to Reduce to Case 1 (\exists Perfect Matching)
 between Exposed Vertices
 in a Max. Matching M in G



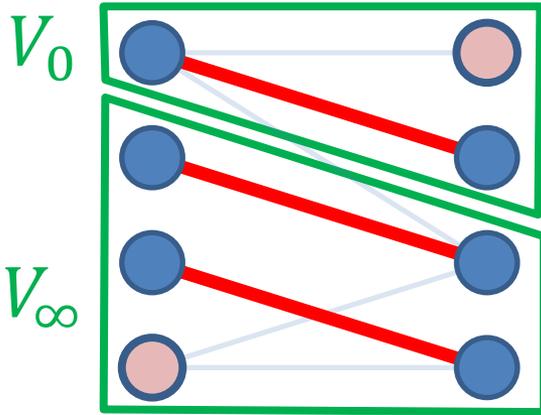
Case 3.1. When $|V^+| = |V^-|$

Idea

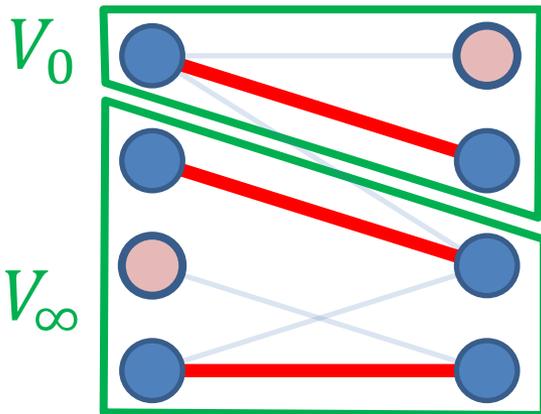
Adding Edges to Reduce to Case 1 (\exists Perfect Matching)
 between Exposed Vertices
 in a Max. Matching M in G



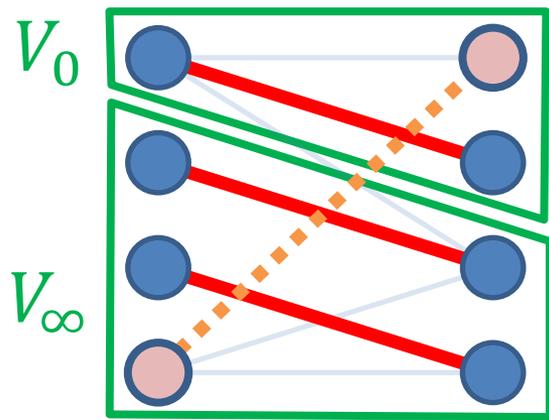
Sources and Sinks in Resulting Digraph



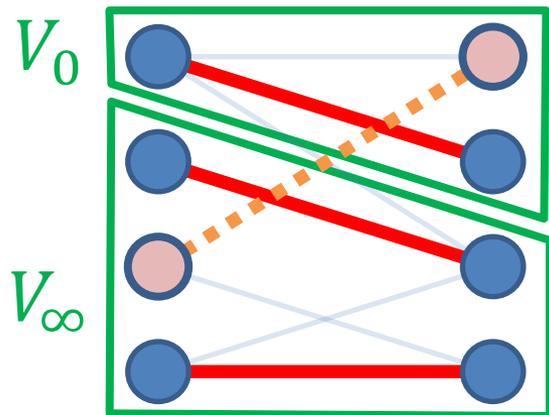
Choice of M



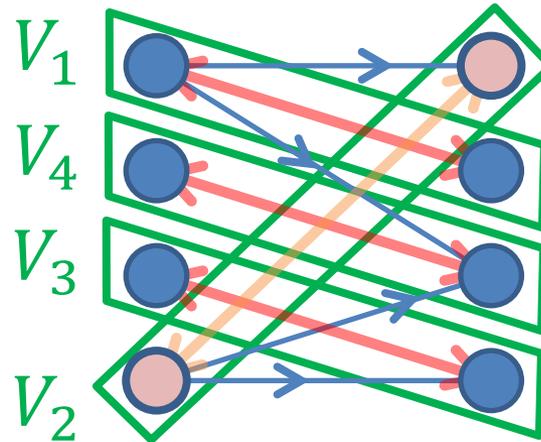
Sources and Sinks in Resulting Digraph



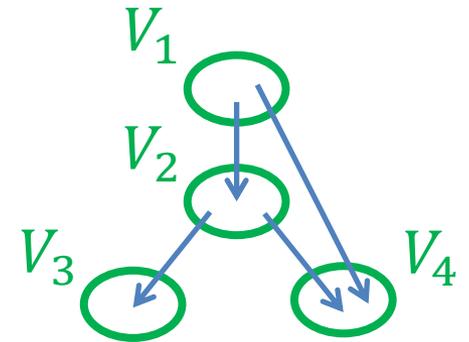
Choice of M



→

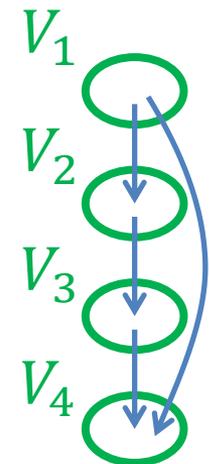
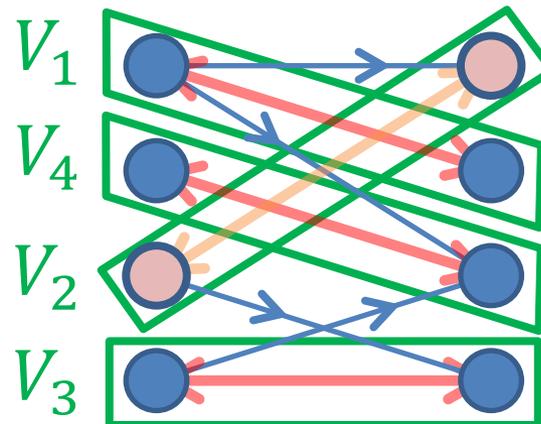


Orientation

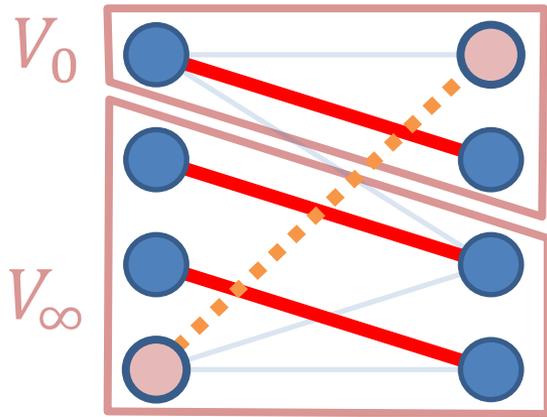


Simplified

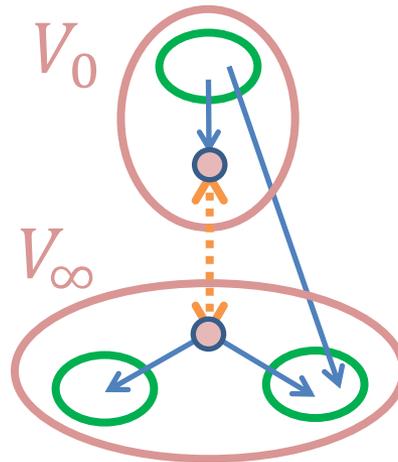
→



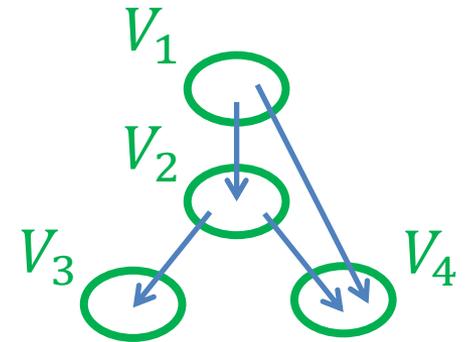
Sources and Sinks in Resulting Digraph



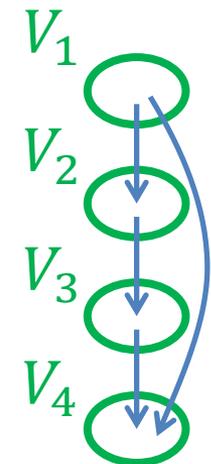
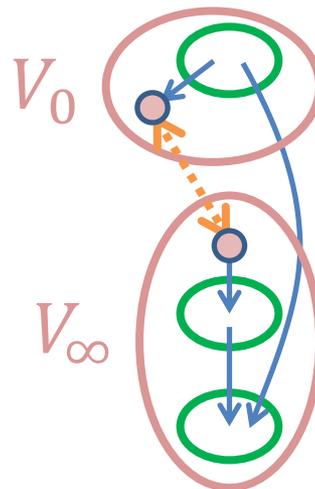
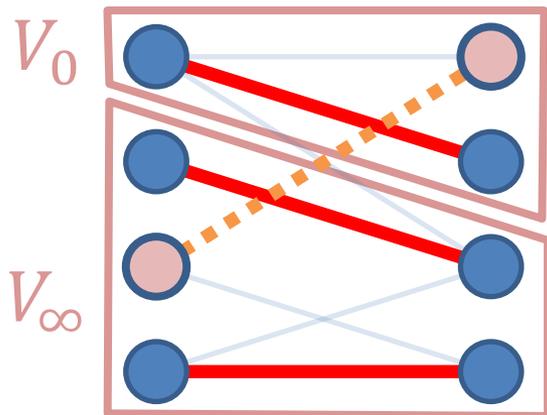
Choice of M



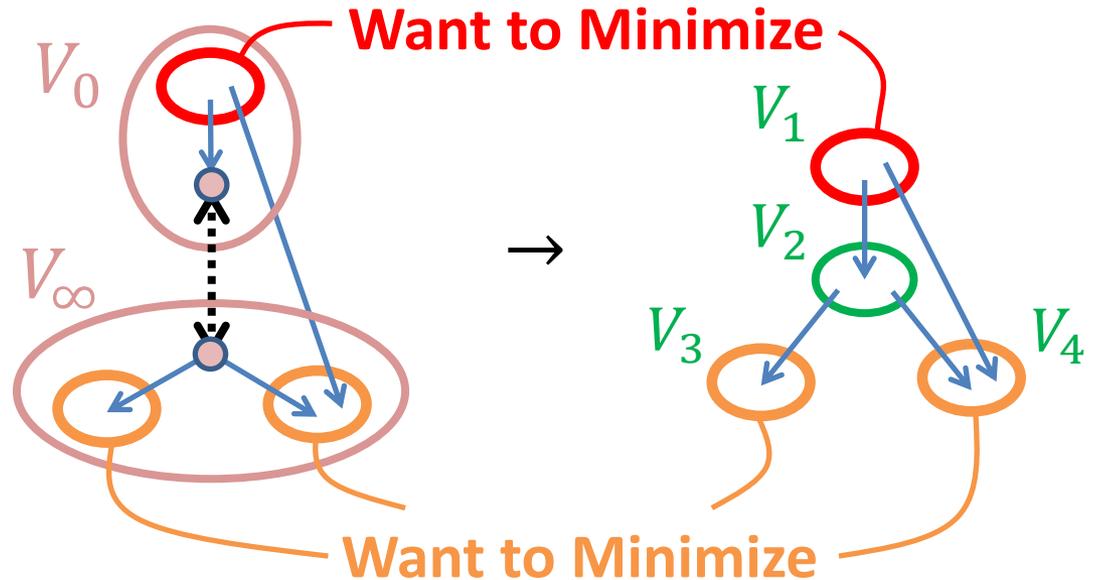
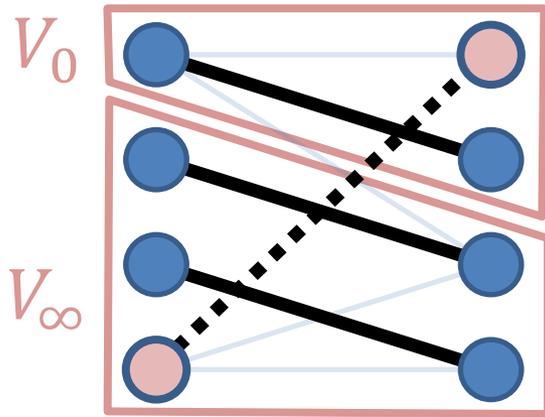
Strg. Conn. Comps.



Simplified



Sources and Sinks in Resulting Digraph

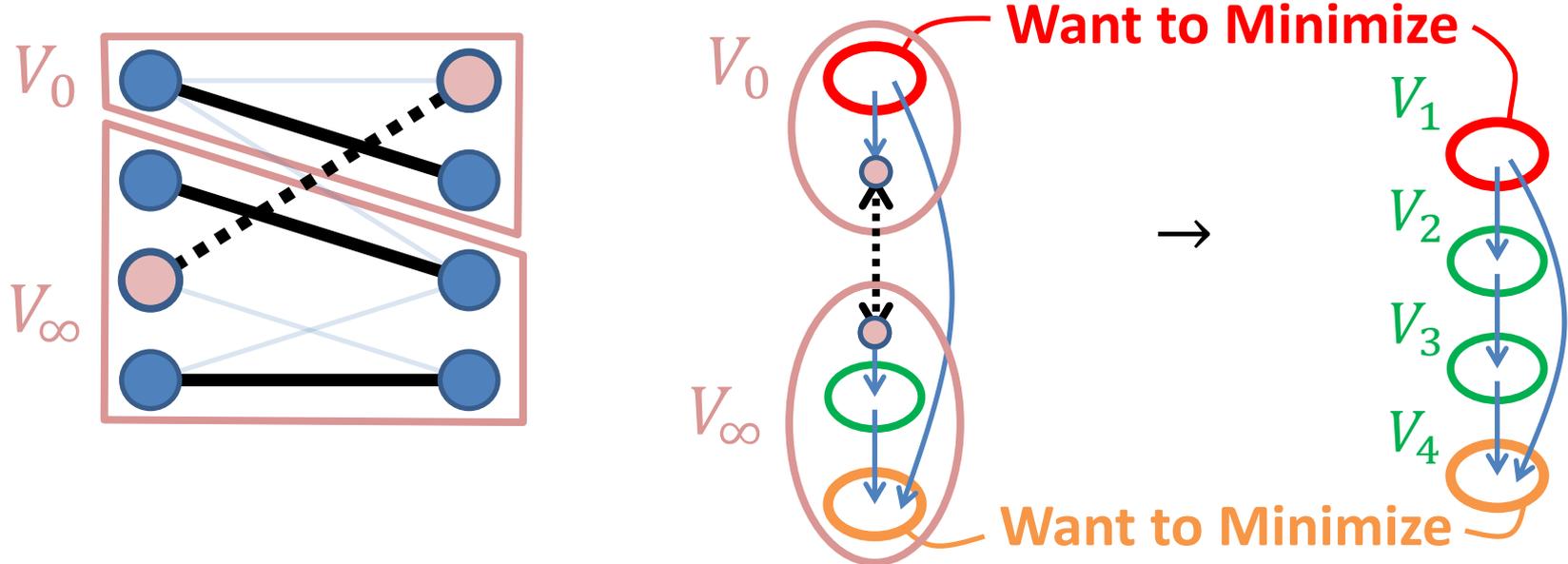


Obs.

(# of **Resulting Sources**) = (# of **Sources in V_0**) + const.

(# of **Resulting Sinks**) = (# of **Sinks in V_∞**) + const.

Sources and Sinks in Resulting Digraph



Obs.

(# of **Sources in V_0**) and (# of **Sinks in V_∞**) vary Indep.
by choices of **Perfect Matchings** in $G[V_0]$ and $G[V_\infty]$.

How to Minimize (# of Sinks in V_∞)

Lem. (# of Sinks in V_∞) is NOT Minimized



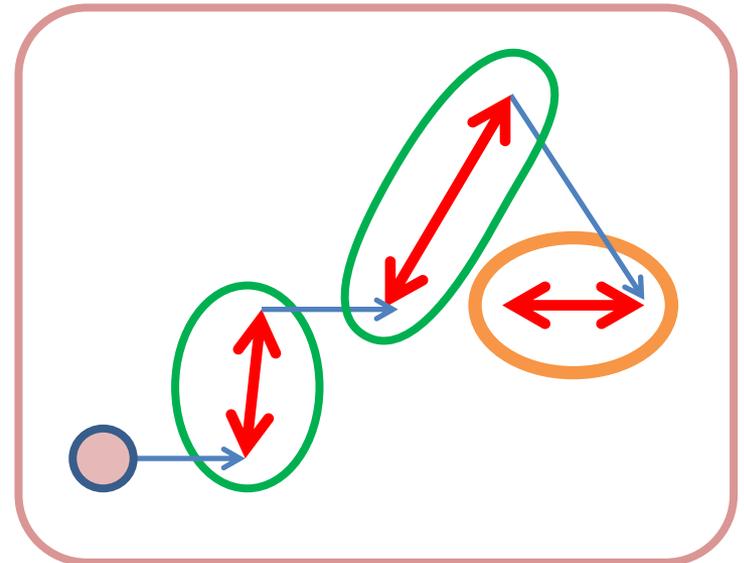
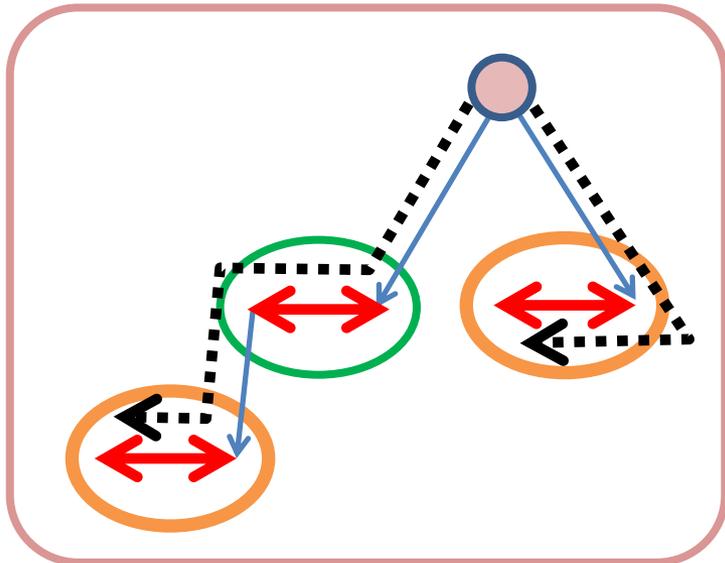
\exists Edge-disjoint Paths from \exists Exposed to \exists Sink₁, Sink₂

[I.-K.-Y. 2016]

-  : Exposed
-  : Sink
-  : S.C.C.

Flipping

V_∞

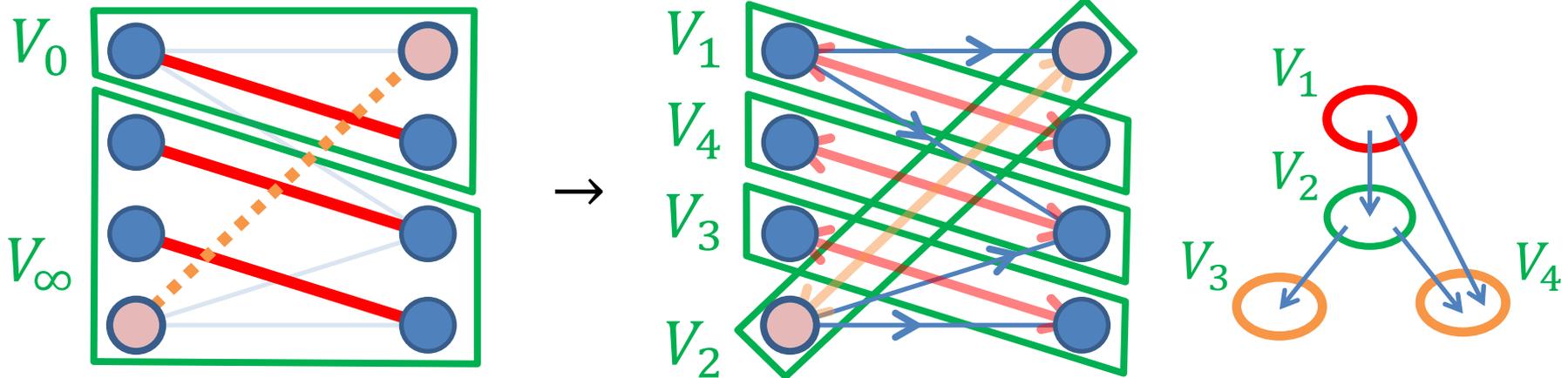


Summary of Cases 3.1

Case 3.1. $|V^+| = |V^-|$ and G has NO Perfect Matching

- Connect Exposed Vertices to Make **Perfect Matching**
→ Reduce to Case 1

$$\text{OPT} = \max\{\# \text{ of Sources, } \# \text{ of Sinks}\}$$



Summary of Cases 3.1

Case 3.1. $|V^+| = |V^-|$ and G has NO Perfect Matching

- Connect Exposed Vertices to Make **Perfect Matching**
→ Reduce to Case 1

$$\text{OPT} = \max\{\# \text{ of Sources, } \# \text{ of Sinks}\}$$

- Minimize ($\#$ of **Sources in V_0**) and ($\#$ of **Sinks in V_∞**), in Advance, by finding Edge-disjoint Paths repeatedly.

Summary of Cases 3.1

Case 3.1. $|V^+| = |V^-|$ and G has NO Perfect Matching

- Connect **Exposed Vertices** to Make **Perfect Matching**
→ Reduce to Case 1

$$\text{OPT} = \max\{\# \text{ of Sources}, \# \text{ of Sinks}\}$$

- Minimize ($\#$ of **Sources in V_0**) and ($\#$ of **Sinks in V_∞**), **in Advance**, by finding Edge-disjoint Paths repeatedly.

Thm. One can find an optimal solution by this strategy.

[I.-K.-Y. 2016]

Outline

- Preliminaries: How to Compute DM-decomposition
 - Find a **Maximum Matching** in a Bipartite Graph
 - Decompose a Digraph into **Strongly Connected Components**
- Result: How to Make a Bipartite Graph DM-irreducible
 - Make a Digraph **Strongly Connected**
 - Find **Edge-Disjoint $s-t$ Paths** in a Digraph
- Conclusion

Conclusion

Given $G = (V^+, V^-; E)$: Bipartite Graph

Find **Minimum Number of Additional Edges**
to Make G **DM-irreducible**

Thm. This problem can be solved in polynomial time.

[I.-K.-Y. 2016]

Tools

- Finding a **Maximum Matching** in a **Bipartite Graph**
- Decomposition into **Strongly Connected Components**
- Making a Digraph **Strongly Connected** by Adding Edges
- Finding **Edge-Disjoint $s-t$ Paths** in a Digraph